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Title of the paper

Validity of a simple sit-to-stand method for assessing force-velocity profile in older adults.

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1 ABSTRACT

2 **Background**: Lower limb muscle strength is an important determinant of physical function in older adults. However, its measure in clinical settings is limited because of the requirement for large-scale and costly 3 4 equipment. A new simple protocol based on sit-to-stand test (STS) is developed to measure force velocity 5 (F-v) and power velocity (P-v) profile in the community-dwelling older adults. **Objective**: The objective of this study was to assess the validity of this new methodology for measuring F-v and P-v profile compared 6 7 to the gold standard isokinetic BIODEX. **Participants**: 46 older people aged 65-85 years (M = 73.7; SD = 8 7.7). Methods: F-v and P-v profiles were assessed in participants on their dominant leg. The concurrent 9 validity of STS was tested using Spearman's rank correlation coefficient and Passing Bablok: maximal power output *Pmax*, optimal velocity and force *Vopt* and *Fopt*, maximal force at null velocity *F0*, maximal 10 unloaded velocity V0 and coefficient of F-v (S_{FV}) and P-v equation (a_poly, b_poly). Results: No 11 proportional difference for F0 and b_poly and a low significant correlation for Pmax (r = 0.314), S_{fv} (r = 12 (0.229), a poly (r=0.335) and b poly (r= 0.226) whereas the other parameters were non correlated 13 significantly. Conclusion: STS method is moderately reliable on force and power parameters whereas 14 15 further improvements are needing for velocity parameters. However, its feasibility, portability and lower cost compared to other methods makes it very affordable in clinical context and will allow easy 16 17 investigation of aging population.

18 Keywords: Force-velocity relationship, simple method, clinical evaluation, sit-to-stand, ageing

19

20 1 INTRODUCTION

The "power-force-velocity" approach is based on force and power-velocity (*F*-v and *P*-v) relationships characterizing maximal mechanical capabilities of lower limbs' neuromuscular systems [1,2]. For now, individual *F*-v profile is widely used in sport performance as it give an optimal individual *F*-v profile that maximizes lower limb ballistic performance which allows individual determination of force or velocity deficit. These profiles could be very interesting to replicate in geriatrics and aging research as measures of
muscle function could allow to screen for an age-related loss of muscle strength and power. Indeed, a loss
of muscle function is related to frailty [3], risk of disability [4], and morbidity in older people, all of which
can lead to a loss of independence in older people.

29 To date, Gold Standard for measuring muscle function in clinical practice and research settings is isokinetic 30 dynamometry [5]. Nevertheless, those systems that measure force and velocity with accuracy are very 31 expensive and time-consuming which limit their spread in clinics. The recent technological progress 32 involving wearable sensors opens the field of possibilities and allows to replace those costly systems with 33 convenient, simple and accurate analysis of the biomechanical kinematic variables. Samozino et al [6] developed their own simple method for having power-force-velocity profiles which can be determined from 34 a series of 2 to 6 loaded vertical squat jumps. In geriatrics, a more adapted exercise is the sit-to-stand (STS) 35 test which is widely used to assess muscle strength [7,8]. Although time to complete STS is the primary 36 measure of function, leg velocity and muscle power also contribute to understanding physical performance 37 38 but require more sophisticated, time-consuming and expensive assessment tools such as force plates [9] 39 and/or motion capture system. To avoid those systems, many studies have attempted to evaluate STS 40 movements with either single or multiple accelerometers, both embedded and in smartphones, placed over 41 different regions of the human body [10,11,12]. Rojas et al [13] characterize velocity profile during STS 42 transitions with an embedded smartphone placed on L2/L3 vertebrae region while Lepetit et al [14] used a single magneto-inertial measurement unit fixed on the chest to quantify velocity, acceleration and kinematic 43 data. All these studies only measure one parameter over leg power, force and velocity which does not allow 44 45 the assessment of *F*-v and *P*-v profiles. To our knowledge, the only study that combines everything is Ruiz-Cardenas et al [15]. They developed an App technology to objectively measure time, velocity and leg power 46 47 during a single STS test. The App was designed for analysing STS via highspeed video recording (240 frames-per-second) allowing the calculation of time between two frames selected by the user and 48 49 subsequent calculation of mean vertical velocity and vertical power relative to body weight.

50 Nowadays, the spread of technology enable the development of simple method by only using smartphones or simple devices. Recently, an open library for real-time multi-person key point detection was proposed 51 52 by Carnegie Mellon University named OpenPose. It is a real-time system to jointly detect 130 human body, 53 hand and facial key points on single images. In addition, its computational performance on body key point estimation is invariant to the number of detected people in the image with high accuracy. OpenPose is freely 54 55 available for all kinds of free non-commercial use [16]. This library enable to have every single joint of the body, angular velocities of the joint, and lower limb forces. In our knowledge, yet, no study has used 56 57 OpenPose to calculate lower limb force and velocity on STS.

As STS has already proved its worth as an effective tool for assessing F-v profiles in clinical geriatric and as OpenPose seems to be a promising one also, combining the two could result in an effective simple method. In this context, the aim of this study was to propose and validate a new simple protocol for determining the *F*-v and *P*-v profiles in the hope of using it to detect decline in physical abilities in older adults. The concurrent validity of this method was tested by comparison to reference isokinetic protocol. We hypothesized that force and power variables will be moderately correlated, velocity variables will be poorly correlated with linear association between them reflecting a sufficient concurrent validity.

65 2 MATERIALS AND METHODS

66 2.1 PARTICIPANTS

A total of 109 community-dwelling older adults aged between 65 and 85 years old were recruited. Exclusion criteria were pathologies that prohibit a maximal strength test, such as severe cardiovascular disease, artificial hip or knee, acute hernia, infection, or tumour. All participant gave written informed consent. Thirty acquisition were not well recorded during STS due to some improper Openpose detection caused by the camera angle, leading to missing data at some velocities (0, 5 or 10kgs). Also, Grubbs test [17] detected 33 recurrent outliers (abnormal STS parameters) resulting in their removal. Finally, 46 participants (6men, 40women) were included in this study (mean age = 73.7 +/- 7.7 years; mean height = 161.8 +/- 8.2 cm;
mean weight = 61.5 +/- 11.4 kgs; mean BMI = 23.5 +/- 4.2 kgs/m²).

75 2.2 EXPERIMENTAL PROTOCOL

Participants were drawn from the *Frailty* project, which aims to identify multidisciplinary markers of aging. Approval of the study protocol was obtained ($n^{\circ} 2015$ -A01188-41). The protocol consists of evaluating *Fv* profiles with Biodex dynamometer system 4 (Biodex Medical Systems, Inc., Shirley, NY) and with STS simple method. The side of healthy or dominant leg for *F*-*v* profile evaluation was chosen to fit with the unilaterality of BIODEX. Thus, hip and knee prosthesis, knee arthrosis and other pathologies were avoided. The protocol included two standardized tests in the following order: STS protocol and Biodex protocol. During each test, participants were clearly instructed by the test leader to perform with maximal effort.

83 2.2.1 Sit-to-stand protocol

84 The tool used was an adjusted chair without backrest. The seat height was visually adjusted to allow the participant to start with a 90° knee angle. A visual line was also placed on the ground to limit feet's 85 displacement during the test. Participants were initially seated on the chair with their back in an upright 86 position wearing their own shoes (in an ecologically situation) (Figure 1). Then, they were instructed to 87 88 stand up as fast as they can with their arms folded across their chest in 3 conditions: with no additional load, with 10kgs load and with 5kgs. All trials were performed using the same chair and with similar ambient 89 90 conditions. They repeated it 3 times to assure to reach maximal velocity during STS and the best of the 3 91 trials was taken. Resting time between the 3 conditions was sufficient to prevent participant from fatigue. A camera was positioned to follow STS movement on their dominant leg unless there was a medical 92 93 contraindication.

94

95 2.2.1.1 Analysis procedure and data recording to sit to stand protocol

Acquisitions were recorded with an Ipad (30hz, 1280x720p). The videos were processed on Python with 96 97 OpenPose library [16]. This library can detect multiple people in real time which is the first time a library can jointly detect key points on human body, face, and foot. The protocol setup was to collect measurements 98 from iPad, to retrieve key points by applying OpenPose "Body25 model" on videos, to preprocess 99 100 (denoising, calculating kinematic parameters) and finally to calculate F-v and P-v profiles. To determine the time point for starting and ending the movement during STS test, plateau were detected on knee flexion 101 extension kinematics. A 0° plateau corresponded to the end of the STS (full extension and a 90° to the start 102 of the movement. The starting point of the STS was determined when a plateau at 90° on knee flexion 103 104 kinematics was detected. The ending point was defined when full extension of knee was achieved in an upright stance corresponding to a 0° plateau. All the F-v and P-v parameters were calculated for one leg to 105 allow comparison with the unilateral single joint BIODEX. With OpenPose, the coordinates (X, Y) over 106 time for shoulder, hip and knee were taken allowing the calculation of their velocities. The associate thigh 107 108 and body force (eg reaction force) for one leg were calculated as followed as well as power P:

109 $F_{thigh} = 0.1416 * p * g$

- 110 $F_{upper_body} = 0.6028*(p+charge)*g$
- 111 With g the gravitational force (9,81 N/kg), p the weight of the participant (kg), charge could be 0, 5 or
- 112 10kgs depending on the wearing jacket and 0.1416 and 0.6028 were taken from the anthropometric De
- 113 *Leva's table* [18].
- 114 $P = M_{upper_body} * v_{upper_body} + 2 * (M_{thigh} * v_{thigh})$
- 115 with M_{upper_body} the net moment joint (F_{upper_body} *d), M_{thigh} as F_{thigh} *d and v the angular velocity
- 116 *of the upper body and thigh respectively.*

117

118 2.2.2 Isokinetic protocol

Measurements were performed unilaterally on the same side of STS protocol. Participants were seated on 119 120 a backward- inclined (5°) and adjustable chair, which is part of the dynamometer (Figure 1). A strap was 121 applied across thigh and hips and shoulders were stabilized with safety belts to avoid additional movements. The rotational axis of the dynamometer was aligned with the transversal knee-joint axis and connected to 122 123 the point of force application at the distal end of the tibia (i.e. 5cm above the lateral malleolus) using a length-adjustable rigid lever arm. Range of motion was set from a knee joint angle of 90° to 160°, with a 124 full extended leg corresponding to a 180° knee angle. Participants were evaluated at six different velocities: 125 126 180° /s, 120° /s, 90° /s, 60° /s, 30° /s to reach an accurate *F-v* profile. Before starting the evaluation, 127 participants performed repetitions to familiarize with knee extension movement and to warm-up.



128

- Figure 1: Isokinetic BIODEX positioning of the participant (a) and STS protocol at Okgs (b), 10kgs (c) and 5kgs with OpenPose skeleton fitting specific body point (d).
- 131 2.2.2.1 Analysis procedure and data recording for isokinetic protocol

Sampling was performed at 100 Hz using an electronic interface card (Biodex Medical Systems Inc., X2151, Shirley, NY, USA). The evaluation on the six different velocities allows to obtain a set of parameters such as the ratio between agonist and antagonist muscles as well as curves representing F-v and P-v relationships.

136 Force (F) – velocity (V) relationship was described by a first order linear equation:

$$F = S_{FV} \cdot V + F0$$

with S_{FV} and b_{linear} the coefficients of the polynomial relation. Note that *F0* is a force corresponding to the theoretical moment at 0° /s velocity value. The velocity value which corresponds to 0 Nm was the maximum theoretical velocity (V_{MAX}).

141 Power (*P*) - velocity (*V*) relationship was described by a second order polynomial equation:

143
$$P = a_poly \cdot V^2 + b_poly \cdot V$$

142 with *a_poly* and *b_poly* coefficients of the polynomial relation (Figure 2).

144 Maximum power (P_{MAX}), and optimal velocity (V_{OPT}) were determined from this equation as:

145
$$V_{OPT} = -\frac{b_poly}{2*a_poly}$$
 and $P_{MAX} = -\frac{b_poly^2}{2*a_poly}$



146



Figure 2: Force-velocity (F-v) and power-velocity (P-v) profiles

148 2.3 DATA ANALYSIS AND STATISTICAL CALCULATION

149 All statistical method comparison was made on *F*-*v* and *P*-*v* parameters which are *Pmax, Fopt, Vopt* and 150 *V0*. We also compared coefficient of *F*-*v* and *P*-*v* equation which are *a_poly* and *b_poly* defined as the 151 quadratic and linear coefficient respectively of *P*-*v* equation and S_{fv} and *F0* defined as the slope and the constant of the linear *F-v* equation. All data were screened for normality using the Shapiro Wilk test. Concurrent validity between STS and BIODEX was assessed by determining Spearman's rank correlation coefficient (r) . The following correlation classification was used: negligible r=0-0.10, low r=0.10–0.39; moderate: r = 0.40-0.69; high: r = 0.70-0.89; very high: r = 0.90-1.0 [19]. Passing-Bablok regression was used to assess the linear association between parameters that succeed to CUSUM test (p>0.05) [20]. All statistical tests were regarded as significant at p<0.05 with a Benjamini-Hochberg correction for multiple associations and statistical analyses were performed using XLSTAT (Addinsoft, New York, USA).

159 **3 Results**

Mean \pm Standard deviation for both STS and BIODEX methods for mean force, velocity and power output are presented in Table 1. Spearman's rank correlation showed no to very low (r= -0.024-0.226) and nonsignificant (p=0.08-0.77) for most of the parameters except for *Pmax* (r = 0.314), *S_{fv}* (r = 0.229), *a_poly* (r=0.335) and *b_poly* (r=0.226) (Table 1). Finally, for all parameters except for *S_{fv}*, p-value of the CUSUM test was more than 0.05 (Table 1) concluding in a linear relation between the two methods. We were thus able to use Passing Bablok regression analysis presented in Figure 3.

The intercept value in Table 2 is a measure of systematic differences between the two methods. The 95% confidence interval containing the value 0 means no systematic difference between the two methods which is not the case for *Pmax, Vopt, F0, V0, S_{fv}* and *a_poly*. Then, it is concluded that the difference between STS and the reference BIODEX method differs at least by a constant amount. For *Fopt* and *b_poly*, the confidence interval is respectively [-111.9; 0.3] and [-123.1; 1.04] concluding in no systematic difference between STS and BIODEX.

- The slope coefficient in Table 2 is a measure of proportional differences between the two methods. The
 95% confidence interval for the slope including 1 means no proportional difference is found. For *Pmax*,
- 174 Fopt, Vopt, V0, S_{fv} and a_{poly} , any of the confidence interval contains 1 concluding in a proportional

175 difference between the two methods whereas for F0, and b_poly , no proportional difference between the

two methods was found.

Table 1: Mean ± Standard deviation and concurrent validity between both methods for mean force, velocity, and power output in one leg.

	Biodex (reference measures)	STS	Spearman's r coefficient	CUSUM test for linearity
Pmax (W)	143.9 +/- 49.9	187.5 +/- 147.3	0.314*	0.124
Vopt (rad/s)	3.6 +/- 0.8	3.3 +/- 3.3	-0.043	0.621
Fopt (N)	39.5 +/- 14.9	36.3 +/- 37.9	0.161	0.05
F0 (N)	83.1 +/- 28.5	62.3 +/- 42.6	0.199	0.387
V0 (rad/s)	7.1 +/- 2.1	6 +/- 7	-0.024	0.109
$S_{fv}(\text{N.s.}\ m^{-1})$	-12.7 +/- 5.1	-4.4 +/- 11.6	0.229*	0.021**
a_poly	-12.7 +/- 5.1	-4.1 +/- 11.7	0.335*	0.05
b_poly	81.7 +/- 28.7	61.8 +/- 43.3	0.226*	0.621

Pmax: Maximal power output against different loading conditions

Vopt: optimal velocity to reach maximal power

Fopt: optimal force to reach maximal power

F0: the theoretical maximal force at null velocity,

V0: the theoretical maximal velocity at which lower limbs can extend during one extension under zero load

 S_{fv} : slope of the F-v relationship

179

a_poly, **b_poly**: coefficient of the P-v relationship

* Significant correlation (p<0.05) (p_value < B-H adjusted p_value)

** non-linear relation between the two methods (p < 0.05) (Passing Bablok not applicable)

Table 2: Passing Bablok model coefficient for Pmax, Vopt, Fopt, F0, V0, S_{fv}, a_poly and b_poly

	Intercept value (95% confidence interval)	Slope coefficient (95% confidence interval)
Pmax (W)	-182 [-408 ; -45.1]	2.4 [1.5 ; 4.2]
Vopt (rad/s)	75.4 [0.7 ; 8.08]	-20.9 [-1.6 ; 0.4]
Fopt (N)	-42.9 [-111.9 ; 0.3] a	2.3 [1.1 ; 4.1]
F0 (N)	-50.7 [-155.2 ; 0.7]	1.4 [0.7 ; 2.8] b
V0 (rad/s)	42.3 [5.1 ; 19.3]	-5.8 [-2.3 ; -0.13]
S_{fv} (N. s. m^{-1})	23 [47.8 ; 9.3]	2.2 [1.1 ; 4.4]
a_poly	22.6 [41.1; 12.2]	2.4 [1.4 ; 3.2]

b_poly	-73.4 [-123.1 ; 1.04] a	1.7 [0.7 ; 2.4] b			
a No systematic difference between the two methods					
b No proportional difference between the two methods					



Figure 3: Passing Bablok regression analysis of the two methods, STS and the reference BIODEX, for Pmax, Vopt, Fopt, F0, V0,
 Sfv, Fmax, a_poly and b_poly. Scatter diagram with regression line and confidence bands. Identity line is dash

183 4 DISCUSSION

The objectives of this study were to assess the concurrent validity of a new method to assess F-v 184 185 and *P*-*v* profiles in older adults based on STS protocol comparing it with the well-known isokinetic protocol. Results obtained highlighted a linear relationship between most of the F-v and P-v parameters between the 186 two methods, no proportional difference for F0 and b_poly and a low significant correlation for Pmax (r = 187 0.314), S_{fv} (r = 0.229), a_poly (r=0.335) and b_poly (r=0.226) whereas the other parameters were non 188 correlated significantly. Results are, thus, encouraging showing a fairly low concurrent validity for 189 parameters of force, power and slope of F-v and P-v relationship (S_{fv} , a_poly and b_poly respectively). 190 191 Spearman's rank correlation was significant but quite low for *Pmax* (r = 0.314, p = 0.017), S_{fv} (r = 192 0.229, p=0.065), a_poly (r=0.335, p=0.012) and b_poly (r=0.226, p=0.065) whereas incongruent and nonsignificant correlation were found for the other parameters. Impellizzeri et al. also found a quite low 193 194 correlation for peak force by comparing a jump test with an isokinetic leg extension (r = 0.48, 95%CI: 0.26-195 0.66) [21]. But when compared to a more similar test (pneumatic leg extension), the correlation is stronger (r=0.83, 95%CI = 0.7-0.91) [21,22,23]. In view of these results, results are consistent with the literature and 196 197 the difference between the two protocols, BIODEX and STS, may strongly impact on the agreement 198 between F-v and P-v parameters. Indeed, when one method (BIODEX) recruited one leg in a closed 199 kinematic chain (isolate knee joint), the other (STS) recruited two legs in open kinematic chain (multiple 200 joints participating to the movement). Studies have demonstrated that mechanical output in leg multi-joint 201 movement is different from that in a single- joint exercise [24]. However, even if methods are quite different, the agreement in *Pmax*, thus the STS calculation, is quite consistent with previous results which 202 203 highlight the capacity of the STS method to determine the mean peak force in community-dwelling older 204 adults. Indeed, the range of magnitude of *Pmax* between BIODEX and STS were very similar (M=143.9W, SD= 49.9W; M=187.5 W, SD=147.3W for BIODEX and STS respectively). The 187.5W found during the 205 STS was for one leg which gave approximately 375W for the entire power developed by the two legs during 206 207 the STS movement. This value was compared to other studies that used different methods for Pmax calculation to check the consistency of this study's protocol. Regarding the range of magnitude, the study's
Pmax appeared to be very closed to the 400W value found in other studies highlighting the consistency of
this value [25,26].

211 The high variability in *Pmax* represented by a SD of +/-147.3W (more than 75% of variability) should also be noticed as, for other studies using STS test, the variability was lower (around 40% in Pmax 212 variability) [27]. The high variability obtained here, which is also extended to all STS parameters, can be 213 214 partly attributed to the STS design protocol used in this study. Indeed, a reasonable variability was found for BIODEX parameters when the range of movement was individually adjusted allowing participants to 215 216 start with a precise 90° knee angle. Also, when Alcazar et al [27] used a standardized armless chair (0.49) 217 m height), a 40% variability was found. In this study, knee angle was not precisely measured even if the 218 start position during STS was visually corrected by the investigator. The starting position visually adjusted 219 was at 85° as a mean in all the participants which highlight that the visual placement at 90° is not perfect. 220 To improve precision, future studies should use the video recording and Openpose to directly correct knee angle and re-adjust chair height to allow participant to begin STS with a precise 90° knee angle which can 221 be done in live. The high STS variability is also explained by the protocol itself where the STS parameters 222 223 were very dependent to the patient stand up velocity whereas for the BIODEX, the patient had to simply 224 follow the pace and the fixed velocity. This contributes to more technical variation in STS execution leading 225 to a high intra-variability thus a lower reliability.

226 The high variability is also participating in the lower reliability results found especially in velocity 227 parameters (Vopt and V0) where no proportional and systematic difference was found in Passing Bablok. Several studies in young and older adults have also reported lower agreement values for VO 228 229 [28,29,30,31,32]. This could be attributable partially to the STS method itself to assess F-v profiles. Indeed, while the F-v profile was assessed by using multiple point (i.e. 6 velocities), the STS was using three points 230 231 (0, 5, 10kgs). Janicijevic et al [32] have recently shown a low concurrent validity of the two-point method, which is quite similar to the three-point, for V0 and F0. When moving from multiple-point methods (usually 232 233 4 to 6 velocities or loads) to a two-point method (or a three-point), the extrapolation between the two-points 234 to construct F-v and P-v slopes is wider than the multiple points providing a larger range of force and velocity data thus a large extrapolation error risk [32]. Also, the model used to fit the F-v relationship was 235 236 the linear model over all the sample (from 0 to 100% of F0) which was largely used in other studies [6,33]. 237 This can be debatable as the linear equation was found to exceptionally fit the F-v shape only between 45 238 to 100% of F0 [34]. Many models have been proposed to fit the F-v relationship with a hyperbolic equation 239 as Hill et al proposed [35] when others demonstrated that the relationship was deviated from this rectangular 240 hyperbola at forces close to the maximal isometric force and that a double-hyperbolic equation was better [36]. It is understandable that the misconception of the shape of the F-v relationship can lead to serious 241 242 errors in the estimation of several parameters derived from linear equations, such as F0 and V0. However, 243 despite this questionable choices, the shape of the STS F-v and P-v equation (*Sfv* and *a_poly* respectively) 244 was found to be correlated (r=0.229-0.335) while other studies found inconsistent results for them (p>0.05) 245 [30,32].

246 Although results are similar to previous works, this method presents some limitations. First, participants were filmed in a side view bounding Openpose on one side to calculate kinematics. This could 247 248 have increase the risk of losing data or abnormal recording if the subject was not well detected. When 249 missing data appeared, it results in extrapolation when calculating F-v parameters that could partially 250 explained the incongruent correlation obtained [28,29]. An improvement could be to place the participant 251 at 45° to the camera to allow Openpose to refer to both right and left sides in order to improve detection 252 thus reliability on calculation. Another limit is that absolute fixed loads were used (5 and 10kgs) instead of 253 relative to body weight to simplify the protocol. It appeared not to correspond to some patients which were 254 removed from the study as the hypothesis of reducing velocities with heavier loads was not always respected. It was for only 30% of the participants but to reduce exclusion, a real time feedback on movement 255 velocity should be given during STS to be sure the hypothesis is well respected [37]. Finally, the study 256 257 design did not allow for a test-rest reliability on STS but previous results seem promising. Indeed, many studies have tested reliability of a STS power test which appears to be excellent (ICC=0.96) [22,23]. Future 258 259 studies should, therefore, test reliability on other F-v parameters than power. It is therefore likely that the observed limited validity in the F-v parameters especially in velocity parameters are caused by extrapolation
error and the combination of technical/instrumental and biological variations that could be easily rectified.

However, for a measurement tool to be widely accepted, factors such as feasibility, safety, and cost 262 263 are just as, if not more, important than measurement properties. Several tools have been used to assess F- ν 264 and P-v profiles in older adults but are very expensive and time-consuming. Indeed, an isokinetic ergometer is feasible with older adults but will take long time (at least 20mn for warm up and protocol) and is 265 266 overpriced (around 80 000\$). A method based on loaded and unloaded squat jump was developed by Samozino et al [6] to assess F-v and P-v profiles with low-cost materials. It has shown to have sufficient 267 268 validity and reliability but there remains safety and feasibility concerns, especially in low functioning older adults. This study was, to our knowledge, the first to propose and validate STS protocol to assess F-v and 269 P-v profiles in older adults and follows in the footsteps Balachandran et al [22] who succeed to develop 270 STS power test in older adults. This method is portable, quicker (around 10mn for the all protocol) and less 271 expensive (estimated at less than 300\$) than the existed methods. 272

As a conclusion, we found better correlation in variables of force and power but not significant in velocities and we shared the same conclusion with better results as other studies that have reported lower or no reliability values for *V0*, *Pmax* or *Sfv* [30,32]. The simple computation method proposed here might offer an inexpensive and easy alternative to assess and individualize *F-v* profiles without the need of expensive technologies in community-dwelling older adults. Future research should investigate if the method is consistent to detect frailty among older adults or future fallers based on *F-v* and *P-v* profiles.

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