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Catastrophic disruptions as the origin of bilobate comets

Stephen R. Schwartz¹, Patrick Michel¹, Martin Jutzi³, Simone Marchi⁴, Yun Zhang^{5,6} and Derek C. Richardson⁶

Several comets observed at close range have bilobate shapes¹, including comet 67P/Churyumov-Gerasimenko (67P/C-G), which was imaged by the European Space Agency's Rosetta mission^{2,3}. Bilobate comets are thought to be primordial because they are rich in supervolatiles (for example, N₂ and CO) and have a low bulk density, which implies that their formation requires a very low-speed accretion of two bodies. However, slow accretion does not only occur during the primordial phase of the Solar System; it can also occur at later epochs as part of the reaccumulation process resulting from the collisional disruption of a larger body⁴, so this cannot directly constrain the age of bilobate comets. Here, we show by numerical simulation that 67P/C-G and other elongated or bilobate comets can be formed in the wake of catastrophic collisional disruptions of larger bodies while maintaining their volatiles and low density throughout the process. Since this process can occur at any epoch of our Solar System's history, from early on through to the present day⁵, there is no need for these objects to be formed primordially. These findings indicate that observed prominent geological features, such as pits and stratified surface layers^{4,5}, may not be primordial.

To investigate the effects of catastrophically disruptive impacts on small outer Solar System bodies, including heating, compaction and the shapes of reaccumulated aggregates, we combined the results of a smoothed-particle hydrodynamics (SPH) code that simulates the fragmentation phase of the disruption and an *N*-body code to simulate the ensuing phase of gravitational reaccumulation. We performed a series of simulations in which we varied the projectile-to-target mass ratio and the impact speed. Table 1 presents the different impact conditions used in our investigation. Although constrained by computational expense, the initial conditions that we chose cover a range of impact speeds that are encountered either in the early Solar System or at later stages. In all cases, they occur at an impact energy that is above the catastrophic disruption threshold so that our results focus on the process of catastrophic disruption.

For the simulations of the fragmentation phase, the objects were initially spherical and made of ice, with an initial density of $0.5\,\mathrm{g\,cm^{-3}}$. Porosity was modelled using a P-alpha model⁶ with a simple quadratic relation using crush curve parameters $P_e = 10^4\,\mathrm{Pa}$ and $P_s = 10^6\,\mathrm{Pa}$, where pressures leave the purely elastic phase above P_e leading to irreversible compaction, and where full compaction is reached at pressures larger than P_s . We used a tensile fracture model⁷ with parameters that lead to an average tensile strength Y_T of ~50 kPa (this is larger than the bulk strength inferred in other

studies⁸ from the tensile strength between the two components of 67P). We note that the collisions considered here can lead to a complete fragmentation of the targets. As shown in previous studies of the disruption regime⁹, the outcomes of such events are not sensitive to the tensile strength. To model fractured, granular material, a pressure-dependent shear strength (friction) was included using a standard Drucker–Prager yield criterion. We used the Tillotson equation of state with parameters for water-ice⁹. This equation of state is adequate for modelling the collisions considered here because the most important response is the compressibility of the material, which is given by the crush curve of the P-alpha model.

To compute an estimate of the temperature increase of the material, ΔT , as a result of the collision, we converted the increase in the specific internal energy, Δu , to a temperature increase using the equation $\Delta T = \Delta u/c_{\rm p}$, where $c_{\rm p}$ is the constant heat capacity, equal to $100\,{\rm J\,kg^{-1}\,K^{-1}}$ (ref. 9)—a mass-weighted average of the heat capacity of ice and silicates. We stress that this approximation only yields reasonable values provided ΔT is small (~100 K or less). For higher temperatures, ΔT is overestimated due to the temperature dependence of $c_{\rm p}$.

The fragmentation process was integrated for 300 s of simulated time, well beyond the point at which the fracture ceased. From here, we defined a constituent particle distribution that included the body's fracture state, velocity distribution and density distribution. We then ported this result into our *N*-body code PKDGRAV^{10,11} as an ensemble of discrete soft-sphere particles¹² using a procedure detailed in previous work¹³, which includes avoiding overlapping particles.

The material friction resistance was controlled by several friction parameters given in our *N*-body model^{12,14}. To show that the validity of our results can be extrapolated to the wide range of friction parameters that may describe these bodies, we intentionally looked at the low end of interparticle friction and used non-cohesive granular material with a friction angle of 18°. Real comets therefore hold their shapes better than the aggregates in our study¹⁵, showing even greater deviation from sphericity and irregular features such as those on 67P.

Our simulations of catastrophic disruptions showed that much of the material from the progenitor bodies reaccumulates after disruption—not necessarily into a single body, but into many smaller bodies. Next, we analysed the shapes and sizes of the reaccumulated aggregates for each simulation. Figure 1 shows that even with relatively low friction and no cohesion between components, dispersed fragments came together to form non-spherical aggregates. Fitting

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Table 1 | Simulations of impact disruptions of comet-like bodies

proj	get-to- jectile ss ratio	Impact speed (m s ⁻¹)	Impact angle (degrees)	Total particles	Total mass (kg)
1/1		20	45	452,544	1.131×10 ¹⁴
2/1		50	45	452,482	1.129×10^{14}
8/1		150	45	451,951	1.128×10^{14}
27/	1	300	45	453,092	1.127×10^{14}
27/	1	1,000	52	453,092	1.127×10^{14}

Comet 67P has a mass of \sim 10¹³ kg²—about 9% of the total progenitor mass in these simulations. Mass ratios and impact angles were chosen to obtain roughly the same degree of disruption in each case.

the aggregate shapes as prolate ellipsoids, the principal axes were on average about 50% greater than their minor axes, but with significant spread. This is in line with what we see in the comet population. Although much of the material contributed to the largest, often elongated remnant, unbound or loosely bound material was also produced, leading to the formation of a multitude of smaller gravitational aggregates (see Supplementary Videos 1–3). We found the specific end-state to be chaotic as it was extremely dependent on initial impact conditions. The extent to which these elongated bodies that form the next generation of comets are made up of distinct 'lobes' depends on (1) whether they originate from two already formed distinct aggregates that merge together and (2) the frictional

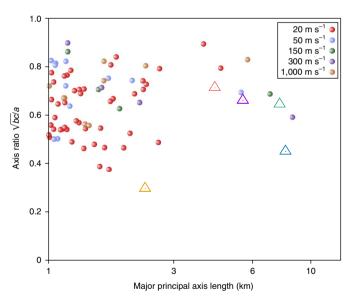


Fig. 1 | Ratio of minor to major principal axes for each reaccumulated body with major axes over 1 km, when fit to a prolate spheroidal shape.

These bodies are typically elongated and irregularly shaped, commensurate with what has thus far been observed of the cometary population^{29–31}. They are also often composed of fragments that originated from regions near to each other inside the progenitors. Aggregates show a distribution of shapes and sizes, with width-to-length ratios ranging from ~0.4–0.9. The elongated shapes are the result of smaller, transitory reaccumulated aggregates that combine at late stages of the reaccumulation process. Friction parameters determine how well these transitory aggregates retain their shapes after combining, and the extent of their bilobate configurations. Shapes and sizes of five comets are also plotted for comparison (open triangles); from left to right, these are: Hartley-2 (ref. ³¹; orange), 67P (ref. ²; red), Wild 2 (ref. ³²; purple), Tempel 1 (ref. ³⁰; green) and Borelly^{33,34} (blue).

properties of the material, namely on the capability of preserving the shapes of the two components while they merge. Therefore, the friction parameters determine how bilobate the final aggregate is. For instance, an angle-of-friction of 29° was needed to form the bilobate shape of Supplementary Video 2. As can be seen from Supplementary Video 1, a lower angle-of-friction of 18° resulted in a more ellipsoidal shape. Supplementary Video 4 shows another example of bilobate body formation that involves the merging of two equally massive aggregates at a late stage in the reaccumulation process to form a final body with mass close to that of 67P. Its shape depends on the conditions of the collision and the friction parameters of the material.

Although we simulated impacts that dispersed the progenitors into many fragments, we found that this did not produce a great deal of heating throughout the body (Supplementary Fig. 1), allowing volatile species to survive the process. Of even more significance, the relatively small fraction of material that was heated substantially was also ejected at higher speeds and did not reaccumulate (Fig. 2; this also agrees with recent work¹⁰ involving less energetic collisions). Figure 2 distinguishes material contained in reaccumulated aggregates based on heating, showing the fraction of material inside aggregates that were heated by a given amount. We found that the amount of heating that a material undergoes correlates tightly with its velocity dispersion, which explains why material that suffers significant heating does not end up in reaccumulated aggregates, small or large. In fact, Fig. 2 also shows that because of this correlation of heating and dispersion, smaller aggregates ('smaller' relative to the resolution in these simulations) contained the least heated material—even less than the material that ended up in the lessgravitationally-weak larger remnants. Therefore, after large-scale catastrophic disruptions, significantly heated material will not be found in the next generation of comets. This suggests that the volatile compounds found inside cometary nuclei can subsist through multiple collisions, including highly energetic catastrophic events, throughout the age of the Solar System.

Similarly, in regard to pore preservation after catastrophic disruption, the regions where material is compacted are typically regions of gravitationally unbound material with a higher initial relative speed that do not easily reaccrete into aggregates. We found that the largest aggregates resulting from the catastrophic disruptions

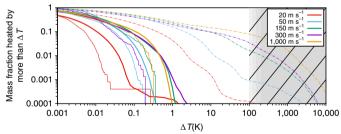


Fig. 2 | Temperature increases resulting from catastrophic collisions at a range of impact speeds. Coloured lines indicate the fraction of material whose temperature rose above the given amount. Dashed lines represent all material from the progenitor bodies, while solid lines represent material that ended up in reaccumulated aggregates. Thick solid lines indicate the temperature increases for material in the larger reaccumulated aggregates shown in Fig. 1. Thin solid lines represent material in small aggregates (the fifty-first to one-hundredth most massive aggregates). When calculating temperature increases, we use a heat capacity relevant for low-temperature material—our focus—thus the data on large temperature increases are not reliable (struck-through region above $\sim \Delta T = 100 \, \text{K}$). See Supplementary Fig. 3 for temperature increases for material inside the largest remnant, including the results from a 3 km s⁻¹ catastrophic disruption scenario.

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investigated here experienced no significant compaction (Fig. 3). Moreover, the creation of macroporosity by gentle reaccumulation of ejected material can lead to an additional increase in the overall porosity by 20–30% ¹⁶. During the collision phase, dilation due to shear failure may further increase porosity ¹⁷.

Catastrophic and marginally catastrophic collisions produce material straddling the limits of their mutual gravity, leading to low-speed mergers and a great variety of final shapes and sizes; this can account for what we observe in today's cometary landscape. Clusters of fragments that initially separate at low speeds relative to each other coalesce during the gravitational phase into the next generation of comets. The relative speeds of these fragments as they reaccumulate are thus also necessarily low (typically under 1 m s⁻¹ for progenitors twice the size of 67P^{18,19}). This allows transient aggregates to keep a memory of their shapes and porosities as they grow during the reaccumulation phase¹⁸. Our simulations show that small fragments gently reaccrete to form many transitory aggregates in the hours and days after a disruption. The eventual shape is often the result of two or more large transitory aggregates coming together and pressing into each other.

Our results offer a clear solution to the problem of the survivability of observed comets^{5,9,20} since collisions with energies sufficient to produce such disruption events could have taken place relatively late in the life of the Solar System. We note that the bilobate or elongated shapes resulting from the disruption of a large body might further evolve in subsequent smaller-scale collisions¹⁶ and/or fission-merging cycles8. Although a recent analysis of crater distributions on Pluto and Charon²¹ suggests a depletion of small (<1 km) trans-Neptunian objects, this would reduce the number of reshaping collisions but have little effect on the number of catastrophic collisions. Thus far, the specific features contained in the images of 67P and resolved by the Rosetta team²² are also commensurate with the catastrophic disruption scenario. Catastrophic collisions could potentially help to explain puzzling observations, such as layering and large-scale fracturing, which otherwise remain a mystery⁵. Widespread fracturing observed in the Hathor region of 67P could

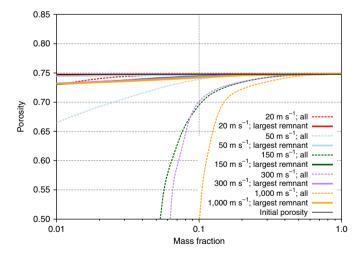


Fig. 3 | Post-impact porosity distributions showing the amounts of mass at a given porosity or below for the catastrophic disruption simulations used in this study. Dashed lines represent material from the entire simulation, while solid lines represent material comprising only the largest remnant. Following previous studies concerning the distribution of compacted material after an impact¹⁶, a reference density for fully compacted material of 1,980 kg m⁻³ was used, which yielded an initial porosity of 75%. Supplementary Fig. 4 includes the results for a 3 km s⁻¹ disruption.

be the result of coherent cracking upon impact, provided a competent piece of the parent body can survive the event. Layering on the comet³ could occur at the end of the reaccumulation process. During this late stage, in the days and weeks following the disruption, and after the body has achieved its overall shape, small aggregates in the vicinity typically continue to reaccumulate onto it in an analogous manner to catastrophic disruption and reaccumulation studies of the inner Solar System4. This continuous process contributes a layering of material onto the surface. In reality, this lateaccreting material may be flattened upon impact with the surface18, leading to a layered structure. Moreover, the accumulation of large blocks at this stage would result in the presence of significant cavities, which could provide nucleation seeds for the large pits23. Thus, in our scenario, the majority of geological features originate naturally from the reaccumulation phase in the wake of a catastrophic disruption event. Current observations should have a limited bearing on the nature of the primordial assemblages. In contrast, since our simulations show that the material itself does not experience significant heating or compaction, its primordial composition remains preserved, in agreement with the classification of comets as primitive bodies²⁴. Although today's catalogue of well-characterized cometary shapes is mostly limited to those we have visited by spacecraft, what we have seen paints a picture that matches a formation scenario involving catastrophic disruption.

Methods

We combined the results of an SPH code that simulates the fragmentation phase of the disruption process and an N-body code (PKDGRAV) to simulate the ensuing phase of gravitational reaccumulation. We performed a series of simulations in which we varied the projectile-to-target mass ratio and impact speed (see main text). The rationale for this hybrid approach is that timescales of fragmentation are very short (typically a few seconds for a kilometre-sized target) compared with the gravitational phase (several days or longer). The computational effort necessary to resolve the impact-induced fragmentation phase in SPH cannot be carried out to simulate the days-long gravitational reaccumulation phase. Also, after fragmentation, the physical regime becomes one dominated by gravity and granular interactions, precisely suited for PKDGRAV. This is a similar approach to one taken for the case of asteroid disruption and reaccumulation. but with meaningful differences (see below) in addition to significant updates to both codes.

The gravitational reaccumulation of material after catastrophic disruption to form asteroid families²⁵ was computed either using a merging procedure that combined two spheres into a single sphere (with a mass of the two colliding spheres) or using a model of rigid aggregates²⁶ that did not truly solve for the contact forces between the reaccumulated particles⁴. We kept track of temperature increases down to particle-scale resolution (around tens of metres; see Supplementary Fig. 1) and used the soft-sphere discrete element method to compute the shapes of resultant aggregates during and after gravitational reaccumulation (Supplementary Fig. 2), as described below.

The fragmentation phase was computed with an improved version of a previous SPH hydrocode⁷, which included a fracture, a friction and a porosity model^{6,27}. The ensuing gravitational phase, during which fragments interacted under their mutual gravity and potentially reaccumulated, was computed with the parallel *N*-body gravity tree-code PKDGRAV^{10,11}. Since our objective was to determine whether bilobate shapes are produced during disruptive events, we needed to explicitly treat the contacts between fragments that reaccumulated so that we could solve for their final shapes in a more realistic way. Thus, we used a version of PKDGRAV that included the soft-sphere discrete element method^{12,28}, while keeping track of all temperature and porosity alterations.

Colliding particles in the soft-sphere discrete element method are permitted to overlap by a small amount (typically <1% of their radii), which can be considered a proxy for the deformation real particles undergo upon collision. The overlapping of particles induces a repulsive force between them that increases with the extent of the overlap. Coefficients of restitution and other material properties (for example, surface roughness and deviation from sphericity) define the magnitudes of the dissipative and frictional forces particles are subject to when in contact (further details of the collisional methodology and explanations of the tree-code methodology and neighbour-finder routines 10,11 are available). In place of the earlier implementation of the rolling friction routine 12 , we used a more rigorous routine 14 , but with the interparticle contact radius in place of the reduced radius for force calculations. Using the radius of contact between particles to compute rolling friction forces rather than the reduced radius causes rolling friction to increase more severely with the extent of overlap and requires a greater value of the parameter β , which quantifies angularity, to achieve the same rolling friction.

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The limits of our current knowledge about the mechanical properties of cometary material mean that the material parameter values are not well defined. Throughout our simulations, we used intermediate values for the normal and tangential restitution coefficients: 0.5 and approximately 0.8, respectively (the coefficient of tangential restitution is not explicitly solved in our soft-sphere discrete element method implementation; see additional discussion in ref. 12). For the stiffness parameters k_n and k_i , which define the grains' resistance to normal- and tangential-axis compression, respectively, we used values of 108 kg s⁻³ and 2.86×10^7 kg s⁻³. To control the number of variables, we kept the twisting friction parameter μ_t = 0. Except when otherwise indicated, we set the Coulomb friction parameter $\mu_s = 1.0$, the rolling friction parameters $\mu_R = 0.5$ and $\beta = 5.0$, and the timestep $\Delta t = 0.5$ s. Many of these values were arrived at through physical constraints (overlaps between colliding particles must be constrained by the choice of k_n and k_n , which in turn determines an upper limit to the timestep), experimentation, and accumulated experience from previous studies—they represent a set of nominal material properties, but future studies could explore a larger parameter space. Also for the sake of limiting the parameter space, and to highlight the generality of our results, we did not include the effects of cohesion between grains or a large size distribution of particles in this study. Both of these are important effects for maintaining the shapes of the fragments after low-speed accumulation. To link the material properties of our simulated aggregates to granular materials, we carried out stress analyses on the aggregates to compute the friction angle for each case¹⁴ (Supplementary Fig. 2).

Data availability. The data that support the plots within this paper and other findings of this study are available from the corresponding author upon reasonable request.

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Author contributions

S.R.S. performed the soft-sphere/*N*-body numerical simulations, analysed the numerical results and led the research. M.J. performed the SPH numerical simulations and contributed to the analyses. P.M. initiated the collaboration between the institutions to investigate catastrophic impacts as an origin story, and helped steer the study to address questions in the context of Solar System origins. S.M. provided essential and detailed context for the Rosetta findings and outstanding questions regarding comet 67P/G–C. Y.Z. analysed the friction angles and implemented the rolling friction subroutine used. D.C.R. guided the development of all *N*-body-related code. All authors contributed to interpretation of the results and preparation of the manuscript.

Competing interests

The authors declare no competing interests.

Additional information

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